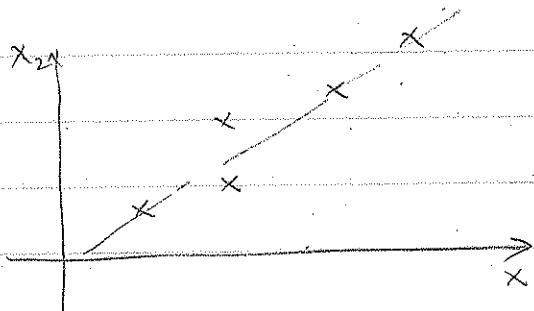


①

DIMENSIONALITY REDUCTION : PCA

① Goal: $\vec{x} \in \mathbb{R}^d \rightarrow \vec{z} \in \mathbb{R}^k$ $k < d$



Often \vec{x} may live in a high-dimensional space \mathbb{R}^d but really occupies a small "lower dimension" subspace or manifold. The above figure show we really measured 1D information (with some noise)

② KL - Transform [No - dim - red yet]

$\vec{x} \in \mathbb{R}^d$ input features
W.L.O.G assume $E[\vec{x}] = 0$

otherwise $\vec{x} \leftarrow \vec{x} - E[\vec{x}]$ "center the data"

Now, Cov matrix $\Sigma_x = E[(\vec{x} - E[\vec{x}]) (\vec{x} - E[\vec{x}])^T]$

$$= E[\vec{x}\vec{x}^T] = \begin{bmatrix} & E[x_i x_j] \\ & E[x_i^2] \end{bmatrix}_{d \times d}$$

Goal: We want to transform features (not project yet)

$\vec{z} = U^T \vec{x}$ where U is an orthonormal matrix

$$U = \begin{bmatrix} | & | & | & | \end{bmatrix}_{d \times d}$$

$$U_i^T U_j = \begin{cases} 0 & \text{if } i \neq j \text{ (orthogonal)} \\ 1 & \text{if } i = j \text{ (unit norm)} \end{cases}$$

Find U s.t. $\vec{z} \in \mathbb{R}^d$ are un-correlated

i.e.

$$\Sigma_{\vec{z}} = \begin{bmatrix} x_1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & x_d \end{bmatrix}_{d \times d}$$

How?

$$\begin{aligned}\Sigma_{\vec{z}} &= E[(\vec{z} - E[\vec{z}])(\vec{z} - E[\vec{z}])^T] \\ &= E[\vec{z}\vec{z}^T] \quad [\text{Recall: } E[\vec{z}] = E[U^T x] = U^T E[x] = 0] \\ &= E[(U^T x)(U^T x)^T] \\ &= E[U^T x x^T U] \\ &= U^T E[x x^T] U = U^T \Sigma_x U\end{aligned}$$

So

$$\Sigma_{\vec{z}} = U^T \Sigma_x U$$

$$\Rightarrow \underbrace{U U^T}_{I} \Sigma_x U = U \Sigma_{\vec{z}}$$

$$\Rightarrow \Sigma_x U = U \Sigma_{\vec{z}} = U \begin{bmatrix} x_1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & x_d \end{bmatrix}$$

$$\Rightarrow \Sigma_x U_i = \lambda_i U_i \quad [\text{Eigen decomposition!}]$$

So Algorithm

$$\rightarrow \begin{bmatrix} U, \lambda \\ \text{evec} & \text{eval} \end{bmatrix} = \text{eig}(\Sigma_x) \quad \Sigma_x = \text{estimated cov matrix from data}$$

$$= \frac{1}{n} \sum \vec{x}_i \vec{x}_i^T \quad \uparrow \text{after ordering}$$

$$\rightarrow \vec{z} = U^T \vec{x}$$

$$\rightarrow \text{Now } \vec{z}_i \text{ are uncorrelated. } E[z_i z_j] = 0$$

$$E[\vec{z}^2] = \lambda_i$$

(2)

2.1 whitening of data

$$\text{Let } \vec{z} = \tilde{\Lambda}^{1/2} U^T \vec{x}$$

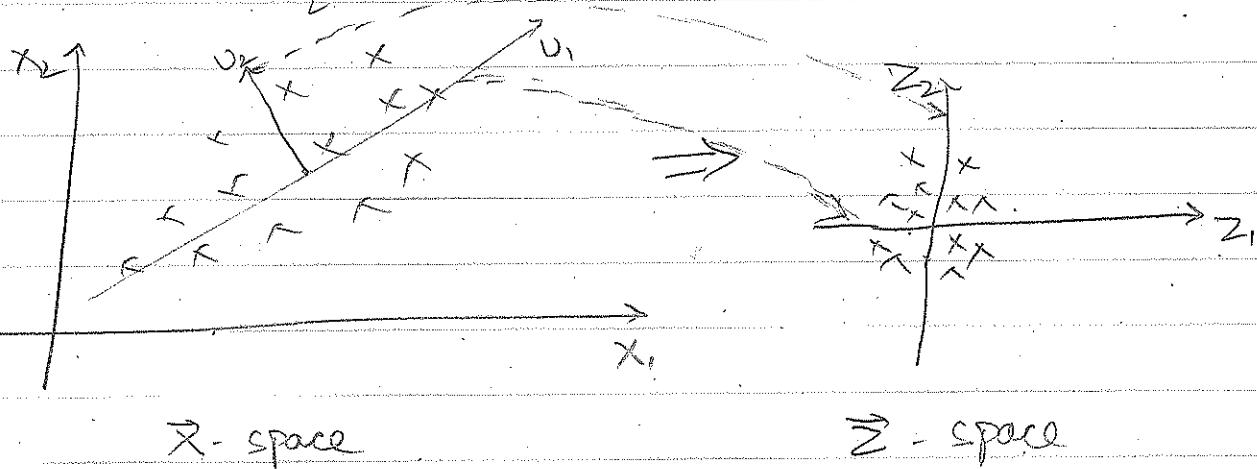
$$= \begin{bmatrix} \frac{1}{\sqrt{\lambda_1}} & & 0 \\ & \ddots & \\ 0 & & \frac{1}{\sqrt{\lambda_d}} \end{bmatrix} \begin{bmatrix} U^T \vec{x} \end{bmatrix}$$

After projecting on $U_1 \dots U_d$
also "normalize" the co-ordinates

$$\text{Now } \Sigma_{\vec{z}} = E[\vec{z}\vec{z}^T]$$

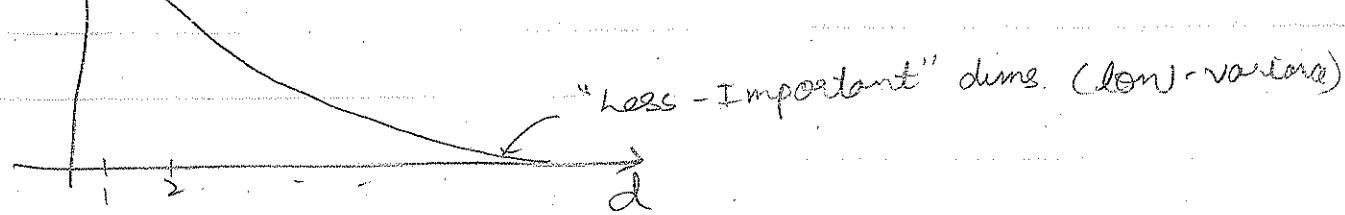
$$= \tilde{\Lambda}^{1/2} \underbrace{U^T \Sigma_{\vec{x}} U \tilde{\Lambda}^{1/2}}_{\begin{bmatrix} x_1 \\ x_d \end{bmatrix}} = I_{d \times d}$$

Ah! data looks
like white noise



Plot of sorted Eigen-values

$\lambda_d \leftarrow$ "Important" dims (high-variance)



③ MAX-VARIANCE VIEW of PCA

Notice in KLT $z = U^T x$

$$= \begin{bmatrix} -U_1^T \\ -U_2^T \\ \vdots \\ -U_d^T \end{bmatrix} x$$

project onto
eig-vectors

Also notice this means $x = U_2 = \underbrace{\begin{bmatrix} y_1 - \bar{y}_2 \\ y_2 - \bar{y}_2 \end{bmatrix}}_{x \text{ as a linear combination of } z}$

How about we reduce dim by ignoring less-variance dims

$$\tilde{z} = \begin{bmatrix} -U_1^T \\ -U_2^T \\ \vdots \\ -U_k^T \end{bmatrix} x$$

top-k only

Formally

$$\max_{\|U_1\|=1} \frac{1}{N} \sum_{i=1}^N (U_1^T x_i)^2$$

[Maximize variance after projection]

Solution
is eigen
vector
again

$$\max_{\|U_2\|=1} \frac{1}{N} \sum_{i=1}^N (U_2^T x_i)^2$$

Find another direction
orthogonal to previous
one

$$\max_{\|U_k\|=1} \frac{1}{N} \sum_{i=1}^N (U_k^T x_i)^2$$

$$\begin{aligned} & U_k^T U_i = 0 \\ & i = 1, \dots, k-1 \end{aligned}$$

(3)

④ MIN-Reconstruction Error View

Note in KLT $\vec{x} = \vec{U}\vec{z}$. If we use d -dims, this give perfect reconstruction of \vec{x} . How about if we use fewer dims?

Formally, find directions U_1, \dots, U_k
 $\vec{z}_1, \dots, \vec{z}_N$ coordinates $\vec{z}_1 \in \mathbb{R}^k, \dots, \vec{z}_N \in \mathbb{R}^k$

$$\begin{aligned} \text{min}_{\vec{U}_1, \dots, \vec{U}_k} \text{error} &= \sum_{i=1}^N \|\vec{x}_i - \tilde{\vec{x}}_i\|^2 \\ &\quad \text{reconstruction} \\ &= \sum_{i=1}^N \|\vec{x}_i - \sum_{j=1}^k \vec{U}_j \vec{z}_j\|_2^2 \end{aligned}$$

↳ Leads to some solution

$$U = \stackrel{\text{top}}{\text{eig-vecs}}$$

$$\vec{z}_i = U^T \vec{x}_i$$



③ PCA via SVD

Consider an image



$$\vec{x}_i \in \mathbb{R}^{10,000}$$

$$\text{So data-matrix } X = \left[\begin{array}{c|c} \vec{x}_1^\top & \\ \hline & \vdots \\ & \vec{x}_N^\top \end{array} \right]_{N \times d} \quad d = 10,000$$

$$\text{PCA requires } \text{eig}\left(\frac{1}{N} X^T X\right) \quad O(d^3)$$

$$\text{SVD of } X \quad X = USV^T = \sum S_{ii} U_i V_i^T$$

orthonormal diagonal orthonormal

Generalization of eigen-values of non-square matrices

Note: $X^T X = (USV^T)^T USV^T$

$$= V S^T U^T U S V^T$$

$$= V S^T S V^T$$

$$= V S^2 V^T$$

$\overset{I}{\sim}$
diagonal
 \Rightarrow symmetric

\Rightarrow S_{ii} is eigen-value of $X^T X$
 & V^T = eigen-vectors of $X^T X$

Economy' SVD can be done in $O(Nd \min(N,d))$ time
 $\equiv O(N^2 d)$ time
 Much-Better!